

# ECE336 – MICROPROCESSORS I

## WEEK 10

### PIC16F84 INTERRUPTS

# INTERRUPTS

- A single microcontroller can serve several devices. In the interrupt method, whenever any device needs the microcontroller's service, the device notifies it by sending an interrupt signal.
- Upon receiving an interrupt signal, the microcontroller stops whatever it is doing and serves the device.
- The program associated with the interrupt is called the interrupt service routine (ISR).

# Interrupt Service Routine

- For every interrupt, there must be a interrupt service routine (ISR), or interrupt handler. When an interrupt is invoked, the microcontroller runs the interrupt service routine.
- Generally, in most microprocessors, for every interrupt there is a fixed location in memory that holds the address of its ISR. In PIC16F84 there is only one location for the interrupt, location 004 (program memory address of the location).

# Steps in executing an interrupt

Upon activation of an interrupt, the microcontroller goes through the following steps:

1. It finishes the instruction it is executing and saves the address of the next instruction (program counter) on the stack register.
2. It jumps to a fixed location in memory (address of the ISR)
3. The microcontroller gets the address of the ISR. It starts to execute the interrupt service subroutine until it reaches the last instruction of the subroutine, which is **RETFIE** (return from interrupt exit).
4. Upon executing the **RETFIE** instruction, the microcontroller returns to the place where it was interrupted. First, it gets the program counter (PC) address from the stack then it starts to execute from that address.

# Sources of Interrupts in the PIC16F84

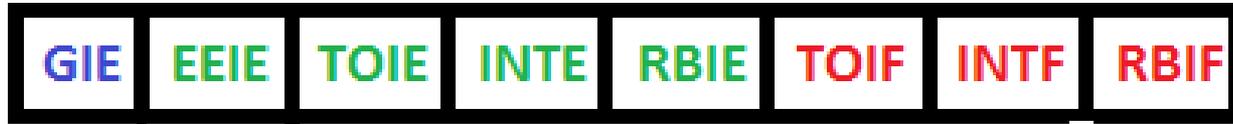
There are many sources of interrupts in PIC16F84, depending on which peripheral is incorporated into the chip. The following are some of the most widely used sources of interrupts in the PIC16F84.

1. External hardware interrupt. Pin RB0 (PORTB. 0) is for the external hardware interrupt INT.
2. There is an interrupt for timer overflow. This is the software interrupt or internal interrupt (when timer register TMR0 counts from h'FF' to h'00').
3. The PORTB-Change interrupt.( RB4,RB5,RB6, and RB7 can be used as interrupt sources. If any bit is changed, interrupt occurs.)
4. EEPROM-interrupt.(It occurs when the writing process is finished)

# INTCON REGISTER

The interrupts must be enabled by software in order for the microcontroller to respond to them. The D7 of the INTCON (Interrupt Control) register is responsible for enabling and disabling the interrupts globally. The following figure shows the INTCON register with all interrupt control bits.

# INTCON REGISTER



## GIE (Global interrupt enable)

GIE=0, disables all interrupts.

GIE=1, interrupts are allowed to happen. Each interrupt source is enabled by setting the corresponding interrupt enable bit.

## EEIE (EEPROM interrupt enable)

EEIE=0, disables EEPROM interrupt

EEIE=1, enables EEPROM interrupt

## TOIE (TMR0 interrupt enable)

TOIE=0, disables TMR0 overflow interrupt

TOIE=1, enables TMR0 overflow interrupt

## INTE (external interrupt enable)

INTE=0, disables external interrupt

INTE=1, enables external interrupt

## RBIE (PORTB interrupt enable for RB4,RB5,RB6,RB7)

RBIE=0, disables PORTB interrupt

RBIE=1, enables PORTB interrupt

These bits, along with the GIE, must be set high for an interrupt to be responded to. Upon activation of the interrupt, the GIE bit is cleared by the PIC16 itself to make sure another interrupt cannot interrupt the microcontroller while it is servicing the current one. At the end of the ISR, the RETFIE instruction will make GIE=1 to allow another interrupt to come in.

## FLAGS OF INTERRUPTS

If **TOIF** =1 there is TMR0 interrupt .

If **INTF**=1 there is external interrupt.

If **RBIF**=1 there is PORTB interrupt.

# ==GENERAL STRUCTURE FOR AN ASSEMBLY PROGRAM WITH EXTERNAL INTERRUPT SUBROUTINE

```
LIST P=16F84A
INCLUDE "P16F84A.INC"
ORG    0X000    ; address of the main program
GOTO   START
ORG    0X004    ;address of the ISR
GOTO   MY_ISR

START

BSF    INTCON, GIE    ;global interrupt enable
BSF    INTCON, INTE   ; external interrupt enable
.....

LOOP
GOTO   LOOP

MY_ISR
BCF    INTCON, INTF   ; clear interrupt flag
.....
RETFIE
END
```

# External interrupts and OPTION register

For external interrupts,

1. RB0 must be input.
2. INTE must be 1.
3. Bit\_6 of the OPTION register (INTEDG) is the interrupt edge select bit;

If INTEDG= 1, interrupt occurs rising edge of the signal. 

If INTEDG= 0, interrupt occurs falling edge of the signal. 

Depends on the hardware, INTEDG must be 0 or 1.

**\*\* To protect the contents of the W register and STATUS register, interrupt subroutine should be written as;**

.....

```
ORG    h'004'  
GOTO MY_ISR
```

.....

MY\_ISR

```
MOVWF    SAVE_W          ; SAVE_W=W_initial  
SWAPF    STATUS,W        ; W=SWAP STATUS_initial  
MOVWF    SAVE_S ; SAVE_S=SWAP STATUS_initial
```

.....

```
SWAPF    SAVE_S, W ; W=STATUS  
MOVWF    STATUS ; STATUS=STATUS_initial  
SWAPF    SAVE_W, F ; W=SWAP W_initial  
SWAPF    SAVE_W, W ; W=W_initial  
RETFIE
```

**Exp.** Write a program that when RA1 is pressed, RB1 is on. If there is an interrupt from RB0/INT (for falling edge), RB2 is toggled.

Exp: Trace the following program and write the output.

```

LIST P=16F84A
INCLUDE "P16F84A.INC"
ORG      0X000      ; address of the main program
GOTO     START
ORG      0X004      ;address of the ISR
BTFSS   PORTA,2
GOTO     MY_ISR1
BTFSS   PORTA,4
GOTO     MY_ISR2
GOTO     MY_ISR3

START
CLRF    PORTB
BSF     STATUS,RPO
CLRF    TRISB
MOVLW   h'FF'
MOVWF   TRISA
BCF     OPTION_REG,INTEDG
BCF     STATUS,RPO
BCF     INTCON,INTF
BSF     INTCON, GIE ;global interrupt enable
BSF     INTCON, INTE ; external interrupt enable

LOOP
GOTO    LOOP

MY_ISR1
BCF     INTCON, INTF ; clear interrupt flag
BSF     PORTB,1
RETFIE

MY_ISR2
BCF     INTCON, INTF ; clear interrupt flag
BSF     PORTB,2
RETFIE

MY_ISR3
BCF     INTCON, INTF ; clear interrupt flag
BSF     PORTB,3
RETFIE
END

```

**Exp:** Write a program that checks all the interrupt sources and executes the related interrupt subroutines.

```

LIST P=16F84A
INCLUDE "P16F84A.INC"
ORG    0X000    ; address of the main program
GOTO   START
ORG    0X004    ;address of the ISR
BTFSC  INTCON,INTF
GOTO   MY_ISR_RB0_INT
BTFSC  INTCON,RBIF
GOTO   MY_ISR_RB
BTFSC  INTCON,TOIF
GOTO   MY_ISR_TO
GOTO   MY_ISR_EE

START
BSF    INTCON, GIE    ;global interrupt enable
BSF    INTCON, INTE   ; external interrupt enable
BSF    INTCON, RBIE   ;PORTB_change interrupt enable
BSF    INTCON, TOIE   ; Timer overflow interrupt enable
BSF    INTCON, EEIE   ;eeprom interrupt enable

.....
LOOP
GOTO   LOOP

```

MY\_ISR\_RBO\_INT

BCF INTCON, INTF ; clear interrupt flag

BSF PORTB,1

RETFIE

MY\_ISR\_RB

BCF INTCON, RBIF ; clear interrupt flag

BSF PORTB,2

RETFIE

MY\_ISR\_TO

BCF INTCON, TOIF ; clear interrupt flag

BSF PORTB,3

RETFIE

MY\_ISR\_EE

BSF PORTB,0

RETFIE

END